

SCANNING OF SPACE GROUPS

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ABSTRACT

Given a crystal whose symmetry group is a three-dimensional space group. We set out a procedure, called *scanning*, by which one can determine the layer group symmetry of all planes in the crystal which are invariant under a two-dimensional subgroup of the translational subgroup of the space group. An example of scanning is given of a crystal with space group symmetry $Cmcm (D_{2h}^{17})$.

Given a three-dimensional Euclidean point space and a three-dimensional space group G defined in this space in a natural coordinate system $(O; T_1, T_2, T_3)$ where O is the origin of the coordinate system and $T_1, T_2,$ and T_3 are a set of generators of the translational subgroup T of G . We set out a procedure to determine all planes in this space which are invariant under a two-dimensional subgroup T_1 of T and the subgroups G_1 of all elements of G which leave each of the planes invariant. G_1 will be called the symmetry group of the plane and a set of generators of the translational subgroup T_1 of G_1 will be denoted by T_{L1} and T_{L2} .

We denote an element of G by $(R | t(R)+T)$ where R is an element of the point group R of G , $t(R)$ is the non-primitive translation associated with R , and T is a translation of the translational subgroup T of G .

Sets of parallel planes are defined by a vector u , a vector perpendicular to the planes. Specific planes are defined by vectors $d = au$ where a is a real number. The vector d is a vector from the

origin to a point on the plane.

A necessary, but not sufficient, condition that a plane defined by a vector d is invariant under an element $(R | t(R)+T)$ of G is that $Rd = \pm d$. Since $d = au$, $Ru = \pm u$ for such elements of G . Consequently, this condition determines the maximal possible point group of planes in the set of planes defined by u , i.e. the maximal possible point group $R_{L_{max}}$ of G_L . For a given u and rotation R of the maximal possible point group $R_{L_{max}}$ we shall determine if there exists planes defined by $d = au$ which are invariant under an element $(R | t(R)+T)$ of G .

We first change the origin of the coordinate system from O to $O+d$, a point on the plane defined by $d = au$. In the natural coordinate system $(O+d; T_1, T_2, T_3)$ an element G of G has the form $(R | t(R)+d-Rd)$. We now introduce a new basis for the natural coordinate system: We define a new set of generators T_{L1}, T_{L2} , and T_3' of the translational subgroup T of G . T_{L1} and T_{L2} are the generators of T_L , the translational subgroup of G_L . Using

$$T = m_1 T_{L1} + m_2 T_{L2} + m_3 T_3'$$

where m_1, m_2 , and m_3 are integers, and

$$t(R) = t(R)_{L1} T_{L1} + t(R)_{L2} T_{L2} + t(R)_3' T_3'$$

$$d-Rd = (d-Rd)_{L1} T_{L1} + (d-Rd)_{L2} T_{L2} + (d-Rd)_3' T_3'$$

we have that the element $(R | t(R)+d-Rd)$ in the natural coordinate system $(O+d; T_{L1}, T_{L2}, T_3')$ is written in component form as:

$$(R \quad t(R)_{L1}+m_1+(d-Rd)_{L1}, \quad t(R)_{L2}+m_2+(d-Rd)_{L2}, \quad t(R)_3'+m_3+(d-Rd)_3')$$

A necessary and sufficient condition that $(R | t(R)+d-Rd)$ is a symmetry element of the plane defined by $d = au$ and is an element of

the group G_t is $t(R)_z' + m_z + (d-Rd)_z' = 0$ which can be written as

$$t(R)_z' + (d-Rd)_z' \stackrel{\circ}{=} 0$$

where " $\stackrel{\circ}{=}$ " means equal to zero modulo one. This condition is used to determine which are the values of a , if any exist, such that $(R | t(R) + T + d - Rd)$ is an element of the symmetry group G_t of the plane specified by the vector $d = au$.

As an example we consider the orthorhombic space group $G = Cmcm (D_{2h}^{1'})$. We choose the natural coordinate system $(O; T_1, T_2, T_3)$ where the generators of the translational subgroup T of G are

$$T_1 = (1/2, 1/2, 0) \quad T_2 = (1/2, -1/2, 0) \quad T_3 = (0, 0, 1)$$

and the origin O is chosen such that coset representatives $(R | t(R))$ of the coset decomposition of G with respect to T can be taken as:

$$\begin{array}{cccc} (E | 0, 0, 0) & (C_{2z} | 0, 0, 1/2) & (C_{2y} | 0, 0, 1/2) & (C_{2x} | 0, 0, 0) \\ (I | 0, 0, 0) & (m_x | 0, 0, 1/2) & (m_y | 0, 0, 1/2) & (m_z | 0, 0, 0) \end{array}$$

We scan along the z -direction by taking $u = (0, 0, 1)$ and consequently $d = a(0, 0, 1)$. The maximal possible point group $R_{tmax} = mmm (D_{2h})$. In the coordinate system $(O+d; T_{11}, T_{12}, T_3')$ where $T_{11} = T_1$, $T_{12} = T_2$, and $T_3' = T_3$, the coset representatives take the form $(R | t(R) + d - Rd)$:

$$\begin{array}{cccc} (E | 0, 0, 0) & (C_{2z} | 0, 0, 1/2) & (C_{2y} | 0, 0, 1/2 + 2a) & (C_{2x} | 0, 0, 2a) \\ (I | 0, 0, 2a) & (m_x | 0, 0, 1/2 + 2a) & (m_y | 0, 0, 1/2) & (m_z | 0, 0, 0) \end{array}$$

Applying condition (1), we have three cases:

1) For an arbitrary value of a , there are two elements which satisfy this condition: $(E | 0,0,0)$ and $(m_x | 0,0,0)$.

2) For $a = P/2$, where P is an arbitrary integer, i.e. $2a \stackrel{\Delta}{=} 0$, we have four elements which satisfy this condition: $(E | 0,0,0)$, $(C_{2x} | 0,0,0)$, $(I | 0,0,0)$, and $(m_x | 0,0,0)$.

3) For $a = (P+1/2)/2$, i.e. $2a + 1/2 \stackrel{\Delta}{=} 0$, we have four elements which satisfy this condition: $(E | 0,0,0)$, $(C_{2y} | 0,0,0)$, $(m_x | 0,0,0)$, and $(m_x | 0,0,0)$.

The symmetry group G_L of a plane $d = a(0,0,1)$ is one of the eighty *Layer Groups*¹. The standard symbols for the Layer Group symmetry of the planes, in the coordinate system $(O+d; T_{11}, T_{12}, T_3')$, for the above three cases are, respectively:

1) $c11m$ in the coordinate system with the x and y coordinates interexchanged.

2) $c112/m$ in the coordinate system with the x and y coordinates interexchanged.

3) $cm2$.

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