## Summary for Lectures 8-9

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## Applications of triple integrals

The applications of triple integrals are also similar to the applications of double integrals. For instance, the volume of a region is the integral of the function $f(x, y, z)=1$ over the region and the mass is given by the integral of a mass density function $\rho(x, y, z)$. The average value of a function is

$$
\bar{f}=\frac{1}{\operatorname{vol}(R)} \iiint_{R} f(x, y, z) d V
$$

and the center of mass $(\bar{x}, \bar{y}, \bar{z})$ is given by

$$
\bar{x}=\frac{1}{\operatorname{mass}(R)} \iiint_{R} x \rho d V
$$

with similar formulas for the other variables.
Notice that the center of mass of a body with an axis of symmetry and constant density must lie on this axis. For example, the center of mass of a circular cylinder of constant density has its center of mass on the axis of the cylinder. In the same way, the center of mass of a spherically symmetric body of constant density is at the center of the sphere.

The formula for the moment of a solid $R$ with mass density $\rho(x, y, z)$ about an axis in three dimensional space is

$$
I=\iiint_{R} d^{2}(x, y, z) \rho(x, y, z) d V
$$

where $d(x, y, z)$ is the distance to the axis.

## Spherical coordinates

In addition to Cartesian and cylindrical coordinates, spherical coordinates are another useful coordinate system for computing triple integrals. They are related to Cartesian coordinates by

$$
x=\rho \sin \phi \cos \theta \quad y=\rho \sin \phi \sin \theta \quad z=\rho \cos \phi
$$

where $\phi$ (between 0 and $\pi$ ) is the angle down from the positive $z$-axis, $\rho$ is the distance to the origin, and $\theta$ is the same angle that appears in cylindrical coordinates. Cylindrical coordinates and spherical coordinates are related by

$$
r=\rho \sin \phi \quad z=\rho \cos \phi \quad \theta=\theta .
$$

The Euclidean volume element in spherical coordinates is given by

$$
d V=d x d y d z=\rho^{2} \sin \phi d \rho d \phi d \theta
$$

and we almost always integrate in this order.

Sections 15.7, 15.8 and 15.9 in Calculus, 7th Edition, by James Stewart

