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# The inverse of a matrix

number of rows = number of columns

Def.

An  $n \times n$  matrix  $A$  is invertible

if

there is an  $n \times n$  matrix  $A^{-1}$  notation

called inverse of  $A$  so that

$$\underline{A \cdot (A^{-1})} = \underline{I_n} = \begin{pmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{pmatrix} = \underline{A^{-1} \cdot A}$$

Similar to:  $5 \cdot \frac{1}{5} = 1 = \frac{1}{5} \cdot 5$

Difference: matrices

do not commute in general

Note: 1. If  $A$  is invertible, then  $A^{-1}$  is also invertible

$$\text{and } (A^{-1})^{-1} = A$$

2. Inverse does not always exist.

For example,  $A = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$  doesn't have inverse

as for any  $B = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ ,  $a, b, c, d \in \mathbb{R}$

$$AB = BA = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

Important!

$A$  is invertible  $\iff$  if we view  $A$  as a map  $\vec{x} \mapsto A\vec{x}$ , then  $A$  is

onto & one-to-one

$\iff$  ~~is~~ pivots in every row and column.

Then If  $A$  is invertible  $n \times n$  matrix, then for each  $\vec{b}$  in  $\mathbb{R}^n$ , the equation  $A\vec{x} = \vec{b}$  has the unique solution  $\vec{x} = A^{-1}\vec{b}$

## ② How do we find inverse?

Row reduction gives an algorithm!

Example Find inverse of  $A$ :

$$A = \begin{bmatrix} 1 & 1 & -1 \\ 1 & 0 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

1. Set matrix with  $A$  on left and Identity on right of the same size as  $A$ .

$$[A : I_3] = \begin{bmatrix} 1 & 1 & -1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 2 & 0 & 0 & 1 \end{bmatrix}$$

2. Bring the part  $A$  of matrix  $[A : I_3]$  to  $I_3$  by row operations (as before just bring  $A$  to RREF). The inverse of  $A$  will be on the part where  $I_3$  was originally ~~the part~~.

$$\begin{bmatrix} 1 & 1 & -1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 2 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 1 \\ 1 & 1 & -1 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 & 1 \end{bmatrix} \rightarrow$$

$$\xrightarrow{R_2 \rightarrow R_2 - R_1} \begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 1 \\ 0 & 1 & -1 & 0 & 0 & -1 \\ 0 & 0 & 2 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_3 \rightarrow \frac{R_3}{2}} \begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 1 \\ 0 & 1 & -1 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 & 0 & 1/2 \end{bmatrix}$$

$$\xrightarrow{R_2 \rightarrow R_2 + R_3} \begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 1 & 0 & -1/2 \\ 0 & 0 & 1 & 0 & 0 & 1/2 \end{bmatrix} \rightarrow A^{-1} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & -1 & 1/2 \\ 0 & 0 & 1/2 \end{bmatrix}$$

③ Note! If you cannot bring A to Identity matrix of the same size, then A is not invertible!

Properties  
 $(A^T)^T = A$   
 $(A+B)^T = A^T + B^T$   
 $(AB)^T = B^T A^T$   
 Then

Properties  
 $(AB)^{-1} = B^{-1} A^{-1}$   
 if A, B are invertible  
 $(A^T)^{-1} = (A^{-1})^T$

Let  $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$

If  $ad - bc \neq 0$ , then A is invertible  
 and  $A^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$ . Then  $A^{-1} = \frac{1}{-2} \begin{bmatrix} 4 & -2 \\ -3 & 1 \end{bmatrix} = \begin{bmatrix} -2 & 1 \\ \frac{3}{2} & -\frac{1}{2} \end{bmatrix}$   
 Example  $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$

If  $ad - bc = 0$ , then A is not invertible.

Def. If A is 2x2 matrix, then  $\text{Det}(A) = ad - bc$  - determinant of A.

Why algorithm described above works?

1. Let  $E_1 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ . What is  $E_1 A$ ?  
 $\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 1 & -1 \\ 0 & 0 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & -1 \\ 0 & 0 & 2 \end{bmatrix}$  corresponds to  $R_1 \leftrightarrow R_2$  in A.

2. Let  $E_2 = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ . What is  $E_2 E_1 A$ ?  
 $\begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & -1 \\ 0 & 0 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 2 \end{bmatrix}$  corresponds to  $R_2 \rightarrow R_2 - R_1$  in  $E_1 A$ .

3. Let  $E_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1/2 \end{bmatrix}$ . What is  $E_3(E_2 E_1 A)$ ?

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1/2 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix}$$

corresponds to

$$R_3 \rightarrow \frac{R_3}{2} \text{ in } E_2 E_1 A.$$

4. Let  $E_4 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$ . What is  $E_4(E_3 E_2 E_1 A)$ ?

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$\underbrace{\hspace{10em}}_{I_3}$

corresponds to

$$R_2 \rightarrow R_2 + R_3 \text{ in } E_3 E_2 E_1 A.$$

We get  $\underline{E_4 E_3 E_2 E_1 A = I_3}$

$E_1, E_2, E_3, E_4$  are called elementary matrices.

Elementary matrices correspond to row operations.

Note!  $A^{-1} = E_4 E_3 E_2 E_1$

Remark!  $\vec{v} \cdot A$

## ⑤ The invertible Matrix Theorem

$A$  -  $n \times n$  matrix.

The following statements are equivalent, i.e., either all true or all false.

- 1)  $A$  is an invertible matrix
- 2)  $A$  is row equivalent to the  $n \times n$  identity matrix  $I_n$
- 3)  $A$  has  $n$  pivot positions
- 4) The equation  $A\bar{x} = \bar{0}$  has only the trivial solution
- 5) The columns of  $A$  form a linearly independent set.
- 6) The linear transform  $\bar{x} \mapsto A\bar{x}$  is one-to-one.
- 7) The equation  $A\bar{x} = \bar{b}$  has at least one solution for each  $\bar{b}$  in  $\mathbb{R}^n$
- 8) The columns of  $A$  span  $\mathbb{R}^n$
- 9) The linear tr.  $\bar{x} \mapsto A\bar{x}$  maps  $\mathbb{R}^n$  onto  $\mathbb{R}^n$
- 10)  ~~$A$~~   $A^T$  is an invertible matrix

## ⑥ Determinants ( $\det(A)$ )

1)  $A$  is  $2 \times 2$  matrix: If  $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$

then  $\det(A) = ad - bc$

$\det(A) \neq 0 \iff A$  is invertible

2)  $A$  is  $3 \times 3$  matrix: If  $A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$ ,

then  $\det(A) = a_{11}a_{22}a_{33} + a_{12}a_{23}a_{31} + a_{21}a_{32}a_{13} - a_{13}a_{22}a_{31} - a_{11}a_{32}a_{23} - a_{21}a_{12}a_{33}$

$\det(A) \neq 0 \iff A$  is invertible

3) ~~What~~ to generalize to  $n \times n$  matrices.

Important property!  $\det(A) \neq 0 \iff A$  is invertible

Geometric interpretation.

Let  $A \in \mathbb{R}^{2 \times 2}$

Thm  $|\det(A)| = \text{Area of parallelogram spanned by } \vec{a}_1 \text{ and } \vec{a}_2$

absolute value

where  $A = \begin{bmatrix} - & \vec{a}_1 & - \\ - & \vec{a}_2 & - \end{bmatrix}$

