REDUCTION OF ORDER

We apply the reduction of order method for the following type of problem:

The second order linear homogeneous differential equation

$$A(t)y'' + B(t)y' + D(t)y = 0,$$

where A(t), B(t), D(t) are some functions, has a known solution $y_1(t)$. Use the **reduction** of order to find the general solution of this differential equation.

Solution.

1. Make coefficient 1 in front of y'' in the given equation, i.e. divide both sides of the equation by A(t).

$$y'' + \frac{B(t)}{A(t)}y' + \frac{D(t)}{A(t)}y = 0.$$
(1)

Therefore, we get an equation in standard form

$$y'' + p(t)y' + q(t)y = 0.$$
 (2)

2. Let us try to find another solution $y_2(t)$ of the given equation, which will be linearly independent from $y_1(t)$, in the following form

 $y_2(t) = y_1(t)v(t)$, where v(t) is an unknown function.

3. Let us compute Wronskian of $y_1(t)$ and $y_2(t)$ by definition

$$W(y_1, y_2)(t) = det \begin{pmatrix} y_1(t) & y_2(t) \\ y'_1(t) & y'_2(t) \end{pmatrix} = det \begin{pmatrix} y_1(t) & y_1(t)v(t) \\ y'_1(t) & y'_1(t)v(t) + y_1(t)v'(t) \end{pmatrix} =$$

= $y_1(t)(y'_1(t)v(t) + y_1(t)v'(t)) - y'_1(t)(y_1(t)v(t)) =$
= $y_1(t)y'_1(t)v(t) + (y_1(t))^2v'(t) - y'_1(t)y_1(t)v(t) = (y_1(t))^2v'(t)$

Therefore, we get that

$$W(y_1, y_2)(t) = (y_1(t))^2 v'(t)$$
(3)

4. Let us compute Wronskian by Abel's theorem

$$W(y_1, y_2)(t) = Ce^{-\int p(t)dt}$$

As we need just one solution linearly independent from $y_1(t)$, we can put C = 1. Therefore, we get

$$W(y_1, y_2)(t) = e^{-\int p(t)dt}$$
(4)

5. We got two expressions (3) and (4) for Wronskian of y_1, y_2 , therefore they should coincide. We set the two expressions equal to each other to get a differential equation on v(t).

$$(y_1(t))^2 v'(t) = e^{-\int p(t)dt}$$
(5)

6. Solve the equation (5) to find v(t):

$$v'(t) = \frac{e^{-\int p(t)dt}}{(y_1(t))^2}$$

$$v(t) = \int \frac{e^{-\int p(t)dt}}{(y_1(t))^2} dt + K$$
, where K is some constant

We can set K equal to 0 as we need just one v(t), which works. Therefore, we can get

$$v(t) = \int \frac{e^{-\int p(t)dt}}{(y_1(t))^2} dt$$

7. After we found v(t), we can write the expression for $y_2(t)$ using v(t) we found:

$$y_2(t) = y_1(t)v(t)$$

8. The general solution of the equation has form

 $y(t) = C_1 y_1(t) + C_2 y_2(t)$, where C_1, C_2 are any constants